A little taste EDA Main ingredient depth functions occorrection of the sector of the s

# Depth in Multivariate Statistics

Ignacio Cascos

Department of Statistics Universidad Carlos III de Madrid

Madrid, February 2019





Outline

#### A little taste EDA

Main ingredient depth functions How to cook them

Full menu applications

Side dishes extensions

In-depth recipe control charts



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# Depth functions

- A depth function quantifies how central a point *x* ∈ ℝ<sup>d</sup> is wrt a multivariate probability distribution (or a data cloud).
- The more central points are assessed high depths, while peripheral ones assume low values of depth.
- Each notion of depth induces a center-outward ordering in a multivariate dataset.
- Many univariate data-analytic techniques can be extended to the multivariate setting by using depth functions.

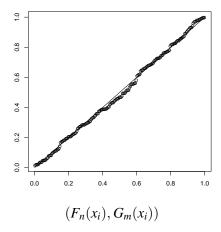




## PPplot & DDplot

#### Liu, Parelius, and Singh, AOS, 1999

PP plot





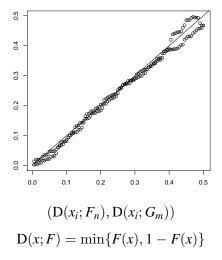
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## **PPplot & DDplot**

#### Liu, Parelius, and Singh, AOS, 1999

DD plot





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### DDplot, Multivariate goodness-of-fit Liu, Parelius, and Singh, AOS, 1999

### A data set and a population distribution

Plot the empirical depth of every point of the data set versus its population depth.

#### Two data sets

Take every point from each of the two data sets and plot its empirical depth wrt the first data set versus the empirical depth wrt the second.

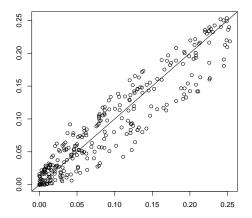


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# DDplot, Multivariate goodness-of-fit

#### Liu, Parelius, and Singh, AOS, 1999



Two data sets drawn from the same distribution.

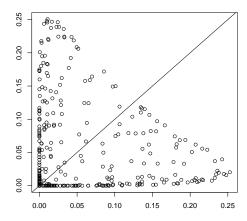


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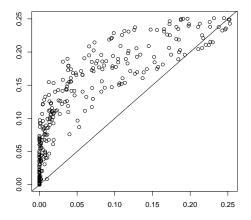


Location shift.

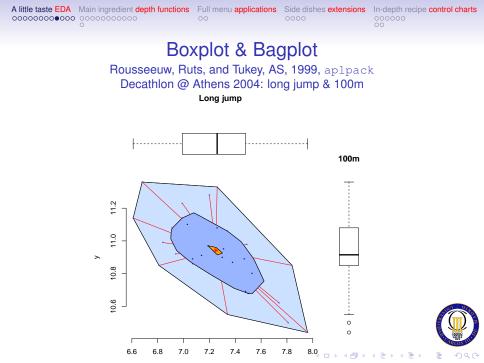
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Shift in scale.

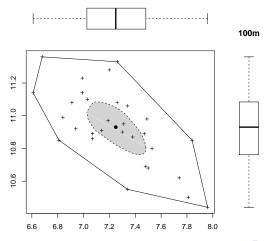




### BEXplot

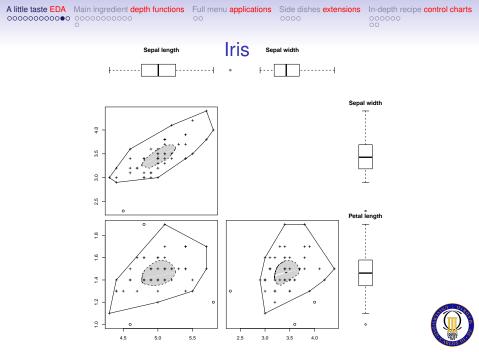
#### Cascos and Ochoa, in preparation

Long jump





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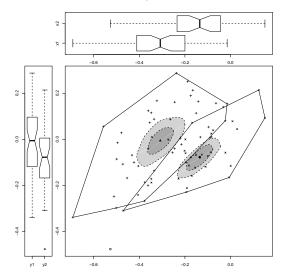


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# Depth function

Liu, AOS, 1990, Zuo and Serfling, AOS, 2000, Dyckerhoff, ASA, 2004

- A depth function, D(x; P) (or D(x) shortly), satisfies:
- D1 Affine invariance.  $D(Ax + b; P_{AX+b}) = D(x; P_X)$  for every nonsingular  $A \in \mathbb{R}^{d \times d}$  and  $b \in \mathbb{R}^d$ ;
- D2 Vanishes at infinity.  $D(x; P) \longrightarrow 0$  if  $||x|| \rightarrow \infty$ ;
- D3 Upper semicontinuity. Level sets are closed;
- D4 Monotonicity relative to deepest point. Decreasing in rays from center;
- D4' Quasiconcavity. Level sets are convex.

The level sets are or depth-trimmed regions are

$$\mathbf{D}^{\alpha}(P) = \{ x \in \mathbb{R}^d : \mathbf{D}(x; P) \ge \alpha \}.$$

Conversely  $D(x; P) = \sup\{\alpha : x \in D^{\alpha}(P)\}.$ 



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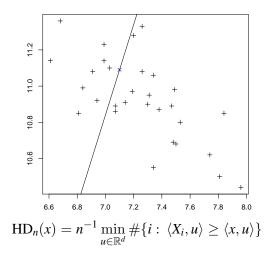
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# Halfspace depth (Tukey, 1975)

#### Decathlon @ Athens 2004: long jump vs. 100m

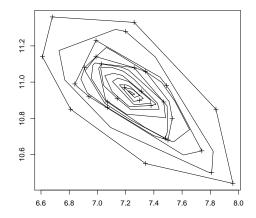




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## Halfspace depth

Tukey, 1975, Rousseeuw and Ruts, Metrika, 1999

Population halfspace depth

 $HD(x; P) = \inf \{ P(H) : x \in H \text{ closed halfspace} \};$ 

- Univariate  $HD(x; P_X) = \min\{F_X(x), 1 F_X(x)\};$
- Satisfies Properties D1–D4 and D4'.

Halfspace trimming

 $HD^{\alpha}(P) = \bigcap \{H : H \text{ closed halfspace } P(H) > 1 - \alpha \};$ 

• Univariate  $HD^{\alpha}(P_X) = [F_X^{-1}(\alpha), F_X^{-1}(1-\alpha)].$ 



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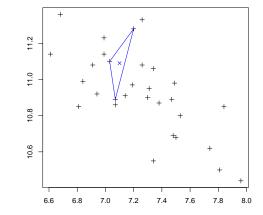
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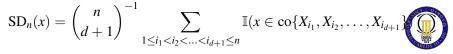


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## Simplicial depth (Liu, AOS, 1990)

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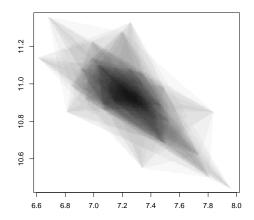




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### Simplicial depth Liu, AOS, 1990

Population simplicial depth

$$\mathrm{SD}(x;P) = \mathrm{Pr}(x \in \mathrm{co}\{X_1, X_2, \dots, X_{d+1}\})$$

where  $X_1, \ldots, X_{d+1}$  are independent with distribution *P*.

- Univariate SD(x; P) = 2F(x)(1 F(x));
- Satisfies D1–D3. Also D4 on absolutely continuous and angularly symmetric distributions.

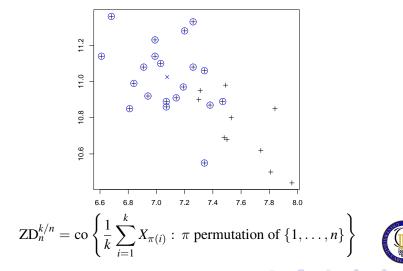


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## Zonoid trimming (Koshevoy and Mosler, AOS, 1997)

#### Decathlon @ Athens 2004: long jump vs. 100m

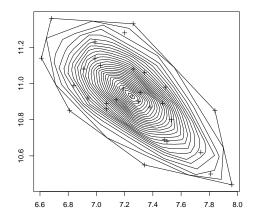


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A little taste EDA Main ingredient depth functions control charts

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# Zonoid trimming

#### Koshevoy and Mosler, AOS, 1997

Population zonoid trimmed regions

$$ZD^{\alpha}(P) = \left\{ \int \mathbf{x} dQ(\mathbf{x}) : Q \text{ probability distribution } Q \le \alpha^{-1}P \right\}$$

Univariate

$$ZD^{\alpha}(P_X) = \left[\frac{1}{\alpha}\int_0^{\alpha} F_X^{-1}(t)dt, \frac{1}{\alpha}\int_{1-\alpha}^1 F_X^{-1}(t)dt\right]$$

- Properties D1–D4 and D4',  $ZD^1(P) = \{EX\}$ .
- Zonoid depth  $ZD(x; P) = \sup\{\alpha : x \in ZD^{\alpha}(P)\}.$



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## How to cook them

- R package depth can be used to compute the halfspace and simplicial depths and to obtain the contour-plots of their level sets as well as the deepest points.
- R package ddalpha contains depth-based classification algorithms and also routines to compute several depth functions, in particular the zonoid depth in dimension *d* ≥ 2.



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# Applications of data depth

- Multivariate EDA (Rousseeuw, Ruts, and Tukey, AS, 1999; Liu, Parelius, and Singh, AOS, 1999)
- Clustering and classification (Ghosh and Chaudhuri, Bernoulli, 2005; Li, Cuesta-Albertos, and Liu, JASA, 2012)
- Outlier detection (Dang and Serfling, JSPI, 2010)
- Inference procedures including control charts (Liu, JASA, 1995; Cascos and López-Díaz, AMM, 2018)
- Imputation of missing data (Mozharovskyi, Josse, and Husson, JASA, 2019)
- Risk measurement (Cascos and Molchanov, FS, 2007)





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## Parameter depth

### Mizera, AOS, 2002; Mizera and Müller, JASA, 2004

- Nonfit: Element from a parameter space that is not a suitable for a parameter wrt a sample.
- Depth: Fraction of points to be deleted from a sample in order to make our candidate a *nonfit*.

### Notions of parameter depth

- Halfspace depth: a nonfit is a point out of the convex hull.
- Regression depth: (Rousseeuw and Hubert, JASA, 1999) a nonfit is a line that does not contain any data point and whose residuals change sign, at most, once.
- Location-scale depth: Mizera and Müller, JASA, 2004.
- Scatter matrices: (Chen, Gao, and Ren, AOS, 2018; Paindaveine and Van Bever, AOS, 2018)



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Parameter depth induced by a probability functional Cascos and López-Díaz, JMVA, 2012

Consider any functional of a probability  $T : \mathbb{P} \mapsto \mathbb{R}^k$ 

• Trimmed regions

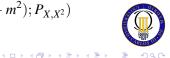
 $D_T^{\alpha}(P) = \{T(Q) : Q \text{ prob. distribution}, Q \le \alpha^{-1}P\}, \text{ for } 0 < \alpha \le 1$ 

• Depth function

$$D_T(x; P) = \sup\{0 < \alpha \le 1 : x \in D_T^{\alpha}(P)\}$$

• Location-scale depth. If *P* is univariate distribution and  $T(P) = (\mu(P), \sigma(P))$ 

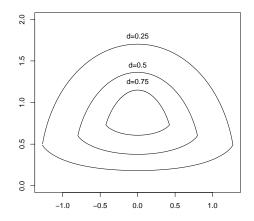
$$LSD((m, s); P_X) = ZD((m, s^2 + m^2); P_{X,X^2})$$



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### Location-scale depth

#### Location-scale regions of levels 0.75, 0.5, and 0.25 wrt a standard normal distribution







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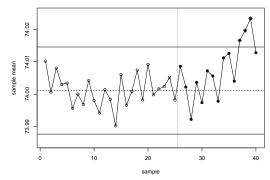
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# Quality Control $\overline{X}$ -chart



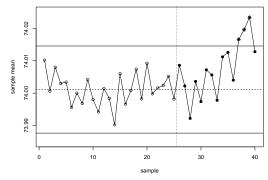
Depth-based multivariate rank

$$r_P(x) = P(\{y : D(y; P) \le D(x; P)\})$$





# Quality Control $\overline{X}$ -chart



Depth-based multivariate rank

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### Quality Control Liu, JASA, 1995

### **Multivariate Control Charts**

• Control Chart for r instead of X-Chart.

$$r_{\hat{P}_m}(X_i) = \#\{Y_j : D_m(Y) \le D_m(X_i)\}/m$$
.

• Control Chart for Q (average rank) instead of  $\overline{X}$ -Chart.

$$\mathcal{Q}(\hat{P}_m; X_1, \ldots, X_k) = \frac{1}{k} \sum_{i=1}^n r_{\hat{P}_m}(X_i) \,.$$

• Control Chart for *S* (accumulated rank) instead of CUSUM Chart.

$$S(\hat{P}_m; X_1, \dots, X_n) = \sum_{i=1}^n \left( r_{\hat{P}_m}(X_i) - \frac{1}{2} \right).$$





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$$Q(\hat{P}_m; X_1, \dots, X_k) = \frac{1}{k} \sum_{i=1}^n r_{\hat{P}_m}(X_i).$$

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Nonparametric control charting based on depth

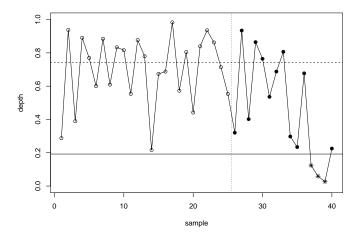
- Control charts for rational samples of size *n*.
- For each sample statistic  $\hat{\theta} = T(\hat{P}_n)$  is monitored.
- Ph. I.1 Build the historical dataset out of the  $m = k \times n$  observations coming from *k* samples of size *n*.
- Ph. I.2 Resample from the historical dataset taking samples of size k in order to estimate the unique CL.
- Ph. I.3 For each trial sample check  $D_m(\hat{\theta}) \ge CL$ . If not, delete the corresponding trial sample and return to step Ph.I.1.
  - Ph. II For each on-going sample, evaluate  $D_m(\hat{\theta})$  and rise an alarm if it lies below CL.



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### Location-scale control chart

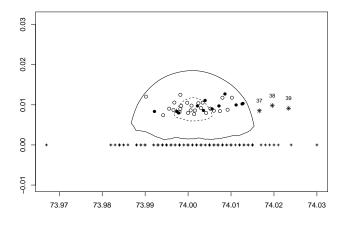




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### Location-scale control chart







# Conclusions

- Data depth refers to the centrality of a point wrt a data cloud (or probability distribution).
- Parameter depth refers to how well does an element of a parameter space fit a probability distribution as its parameter.
- Applications of data depths and parameter depths have been briefly introduced.



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## Acknowledgements

# Thank you!!



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