Modeling Risk: The heartbreak of asymptotic independence

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Introduction: Finding Hidden Risks

1.1. Background.

Suppose

$$\boldsymbol{X} = (X_1, \dots, X_d)$$

is a risk vector. Imagine X_i is

- loss from *i*th asset in portfolio;
- concentration of *i*th pollutant;
- car maker's warranty exposure over a month for ith car model in lineup.

Goal: Estimate the probability of a risk region \mathcal{R}

$$P[X \in \mathcal{R}]$$

where \mathcal{R} is beyond the range of observed data.



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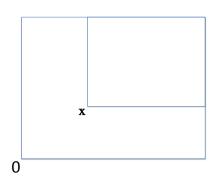
Example:

d=2 and

$$\mathcal{R} = (\mathbf{x}, \mathbf{\infty}] = (x_1, \infty] \times (x_2, \infty]$$

and

$$P[X \in \mathcal{R}] = P[X_1 > x_1, X_2 > x_2].$$



Risk contagion: Can two or more components of the risk vector \boldsymbol{X} be simultaneously large? Typically,

large=beyond the range of the data.



2. Mathematical foundation: Regularly varying functions and measures

2.1. Regularly varying functions

A function $U: \mathbb{R}^d_+ \to \mathbb{R}_+$ is multivariate regularly varying if

$$\lim_{t \to \infty} \frac{U(t\mathbf{x})}{U(t\mathbf{1})} = \lambda(\mathbf{x}) \neq 0,$$

for $x \ge 0$, $x \ne 0$.

• If d = 1, limit must be a power function and we are dealing with functions U which are asymptotically like power functions; for d = 1,

$$\frac{U(tx)}{U(t)} \to x^{\rho}, \quad \rho \in \mathbb{R}.$$

Call ρ the index and when d=1 we write $U \in RV_{\rho}$.

• When d > 1, a scaling argument shows $\exists \rho \in \mathbb{R}$ and

$$\lambda(t\mathbf{x}) = t^{\rho}\lambda(\mathbf{x}),$$

and $U(t\mathbf{1}) \in RV_{\rho}$.



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– Therefore, equivalent formulation is there exists $V \in RV_{\rho}$ such that

$$\frac{U(t\mathbf{x})}{V(t)} \to \lambda(\mathbf{x}) \neq 0.$$

- Possible choice: $V(t) = U(t\mathbf{1})$.
- Sequential version when $\rho > 0$): $\exists b_n \to \infty$ such that

$$\frac{U(b_n\mathbf{x})}{n} \to \lambda(\mathbf{x}).$$

- Can set $b_n = V^{\leftarrow}(n)$.



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2.2. Connection to domain of attraction (DOA) characterizations.

Suppose $\{X_n, n \geq 1\}$ are iid non-negative, common distribution function F(x). The extreme is

$$M_n = \bigvee_{i=1}^n X_i = \max\{X_1, \dots, X_n\}.$$

One of the extreme value distributions is the Frechet:

$$\Phi_{\alpha}(x) := \exp\{-x^{-\alpha}\}, \quad x > 0, \ \alpha > 0.$$

Questions:

• What are conditions on F, called domain of attraction conditions, so that there exists $b_n > 0$ such that

$$P[b_n^{-1}M_n \le x] = F^n(b_n x) \to \Phi_\alpha(x).$$
 (DOA-frechet)

When (DOA-frechet) holds, we say F is in the domain of attraction of Φ_{α} and write $F \in D(\Phi_{\alpha})$.

• How do you characterize the normalization sequence $\{b_n\}$?



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Answers:

• DofA: One argues that we must have

$$x_0 = \sup\{x : F(x) < 1\} = \infty,$$

and furthermore

$$b_n \to \infty$$
.

In (DOA-frechet), take logarithms to get for

$$\lim_{n \to \infty} n(-\log F(b_n x)) = x^{-\alpha}, \quad x > 0.$$

Use

$$-\log(1-z) \sim z, \quad (z \to 0,$$

and (DOA-frechet) is equivalent to

$$\lim_{n \to \infty} n(1 - F(b_n x)) = x^{-\alpha}, \quad x > 0.$$
 (1)

This is the sequential version of regular variation for $\bar{F} := 1 - F$.

• Characterize b_n : Set U(x) = 1/(1 - F(x)) and (1) is the same as

$$U(b_n x)/n \to x^{\alpha}, \quad x > 0,$$

and inverting, we find that

$$\frac{U^{\leftarrow}(ny)}{b_n} \to y^{1/\alpha}, \quad y > 0. \tag{2}$$



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Conclude:

$$U^{\leftarrow}(n) = (1/(1-F))^{\leftarrow}(n) = F^{\leftarrow}(1-\frac{1}{n}) \sim b_n$$

and this determines b_n (convergence to types theorem).

2.2.1. Summary: Connecting regular variation and domains of attraction in one dimension.

With

$$\Phi_{\alpha}(x) = \exp\{-x^{-\alpha}\}, \quad x > 0, \ \alpha > 0,$$

we have

$$F \in D(\Phi_{\alpha}) \text{ iff } \lim_{t \to \infty} \frac{\bar{F}(tx)}{\bar{F}(t)} = x^{-\alpha}, \ x > 0;$$

that is, $\bar{F} \in RV_{-\alpha}$.



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2.3. Behavior of one dimensional regularly varying functions:

Regularly varying functions behave asymptotically like power functions. Helpful notation: Call L(x) slowly varying if $L(\cdot) \in RV_0$. Then if

$$U \in RV_{\rho}$$

we have

$$L(x) := U(x)/x^{\rho} \in RV_0$$

and we can write

$$U(x) = x^{\rho}L(x).$$

Rules for manipulating:

• Karamata theorem: For $\rho > -1$,

$$\int_0^x U(t)dt$$

behaves as if L(t) comes out of the integral and the power part



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integrates. So if $U(x) = x^{\rho}L(x)$, then

$$\int_0^x U(t)dt = \int_0^x t^{\rho} L(t)dt$$

$$\sim L(x) \int_0^x t^{\rho} dt = L(x) \frac{x^{\rho+1}}{\rho+1}$$

$$= \frac{xU(x)}{\rho+1}.$$

- Differentiation: If $U \in RV_{\rho}$ has a monotone density u(x), then $u(x) \in RV_{\rho-1}$ (as if it were a power function).
- Regularly varying functions have smooth asymptotically equivalent versions which comes from the *Karamata representation*: if $U \in RV_{\rho}$,

$$U(x) = c(x) \exp\{\int_{1}^{x} \frac{\rho(s)}{s} ds\},\,$$

where

$$c(x) \to c_0, \quad \rho(t) \to \rho.$$

So

$$U(x) \sim c_0 \exp\{\int_1^x \frac{\rho(s)}{s} ds\},$$

and the right side can be made as smooth as one likes (eg, infinitely differentiable).



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• The regular variation ratio converges locally uniformly; eg, if $U \in RV_{\rho}$,

$$\lim_{t \to \infty} \frac{U(tx)}{U(t)} = x^{\rho},$$

uniformly on [a, b], $0 < a < b < \infty$.

- If $\rho < 0$, uniform convergence on $[b, \infty)$, b > 0.
- Inversion: If $U \in RV_{\rho}$, $\rho > 0$, regular variation $U \in RV_{\rho}$ implies $U^{\leftarrow} \in RV_{1/\rho}$:

$$\lim_{t \to \infty} \frac{U^{\leftarrow}(tx)}{U^{\leftarrow}(t)} = x^{1/\rho}.$$



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2.4. Multivariate Regular Variation for Multivariate Distribution Functions and Measures on \mathbb{R}^d_+

Application to distributions: Let Z be a random vector in \mathbb{R}^d_+ with df F. A regularly varying tail means

$$\frac{1 - F(t\mathbf{x})}{1 - F(t\mathbf{1})} \to \nu_*([\mathbf{0}, \mathbf{x}]^c),$$

for some Radon measure ν_* . Awkward to deal with multivariate df's and better to deal with measures. Let

$$\mathbb{E} = [0, \infty]^d \setminus \{\mathbf{0}\}$$

$$\aleph = \{\mathbf{x} \in \mathbb{E} : ||\mathbf{x}|| = 1\} \qquad \text{(unit sphere)},$$

$$R = ||\mathbf{Z}||, \quad \Theta = \frac{\mathbf{Z}}{||\mathbf{Z}||} \in \aleph \qquad \text{(polar coordinates)}.$$

The following are equivalent.

1. \exists a Radon measure ν_* on \mathbb{E} such that

$$\lim_{t \to \infty} \frac{1 - F(t\mathbf{x})}{1 - F(t\mathbf{1})} = \lim_{t \to \infty} \frac{\mathbb{P}\left[\frac{\mathbf{Z}_1}{t} \in [\mathbf{0}, \mathbf{x}]^c\right]}{\mathbb{P}\left[\frac{\mathbf{Z}_1}{t} \in [\mathbf{0}, \mathbf{1}]^c\right]}$$
$$= c\nu_* \left([\mathbf{0}, \mathbf{x}]^c\right),$$



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some c > 0 and for all points $\mathbf{x} \in [\mathbf{0}, \infty) \setminus \{\mathbf{0}\}$ which are continuity points of $\nu_*([\mathbf{0}, \cdot]^c)$.

2. \exists a function $b(t) \to \infty$ and a Radon measure ν_* on \mathbb{E} such that in $M_+(\mathbb{E})$

$$t\mathbb{P}\left[\frac{\mathbf{Z}}{b(t)} \in \cdot\right] \stackrel{v}{\to} \nu_*, \quad t \to \infty.$$

3. \exists a pm $S(\cdot)$ on \aleph and $b(t) \to \infty$ such that

$$t\mathbb{P}[\left(\frac{R}{b(t)}, \boldsymbol{\Theta}\right) \in \cdot] \stackrel{v}{\to} c\nu_{\alpha} \times S$$

in $M_+(((0,\infty] \times \aleph))$, where c > 0.

Notes:

- Can replace function b(t) by sequence b(n).
- $\stackrel{v}{\to}$ means vague convergence defined as follows: Let $M_+(\mathbb{E})$ be the Radon measures on \mathbb{E} . (Radon means the measure is finite on relatively compact sets.) $M_+(\mathbb{E})$ can be metrized by vague convergence: Let $\mu_n(\cdot), n \geq 0$ be measures in $M_+(\mathbb{E})$. Then

$$\mu_n \stackrel{v}{\to} \mu_0$$



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iff

$$\mu_n(f) := \int_E f d\mu_n \to \int_E f d\mu =: \mu(f) \quad (n \to \infty)$$

for all non-negative, continuous functions with compact support on \mathbb{E} .

• Generally, vague convergence can be reduced to convergence of measures on a class of rectangles suited to the compact sets of \mathbb{E} .



These conditions imply:

for any sequence $k = k(n) \to \infty$ such that $n/k \to \infty$ we have

4. In $M_+(\mathbb{E})$,

$$\frac{1}{k} \sum_{i=1}^{n} \epsilon_{\mathbf{Z}_i/b\left(\frac{n}{k}\right)} \Rightarrow \nu \tag{*}$$

$$\frac{1}{k} \sum_{i=1}^{n} \epsilon_{(R_i/b(n/k),\Theta_i)} \Rightarrow (c\nu_{\alpha} \times S). \tag{**}$$

and (4) is equivalent to any of (1)–(3), provided $k(\cdot)$ satisfies $k(n) \sim k(n+1)$.

Ignore fact $b(\cdot)$ unknown:

- \rightarrow LHS of Eqn (*) is a consistent estimator of ν .
- \rightarrow From (**), consistent estimator of S is

$$\frac{\sum_{i=1}^{n} \epsilon_{(R_i/b(n/k),\Theta_i)}[1,\infty] \times \cdot)}{\sum_{i=1}^{n} \epsilon_{R_i/b(n/k)}[1,\infty]}.$$

We need the following:

Let \mathbb{C} be a closed cone in \mathbb{R}^d_+ ; that is,

$$\mathbf{x} \in \mathbb{C} \implies t\mathbf{x} \in \mathbb{C}, \quad \forall t > 0.$$



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The random vector $\mathbf{Z} \in \mathbb{R}^d_+$ has a distribution tail which is regularly varying on \mathbb{C} with limit measure $\nu_{\mathbb{C}}(\cdot)$ if for nice sets $A \subset \mathbb{C}$ we have

$$tP[\frac{\mathbf{Z}}{t} \in A] \to v_{\mathbb{C}}(A).$$

Example: $\mathbb{C} = (\mathbf{0}, \infty]$.



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2.5. Statististical difficulty.

- This formulation is good for theory but bad for applications.
- Being able to norm each component by the same b(t) means marginal tails are the same—almost never happens in practice. Multivariate data from a distribution with heavy tailed marginals, never have the same α 's.
 - Set

$$\mathbf{Z} = (Z^{(1)}, \dots, Z^{(d)}).$$

Norming each component with the same b(t) means

$$\mathbb{P}[Z^{(i)} > x] \sim c_{ij} \mathbb{P}[Z^{(j)} > x], \quad x \to \infty.$$

and if $c_{ij} > 0$, then the tail index of $Z^{(i)}$ and $Z^{(j)}$ are the same.

- Not true in practice. And what is the dependence structure?
- Examples:
 - Absolute returns Xchr vs USD of (FR, JAP).
 - (Size of document downloaded, download time); etc.



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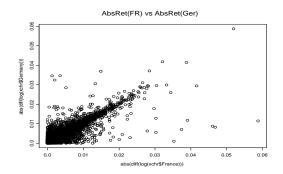
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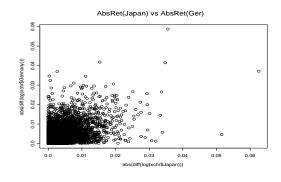
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Absolute log-returns forex 2 Eurpean currencies (prior to Euro)

- Daily absolute logreturns of French franc vs German mark against the USD.
- Jan 1971 Feb 1994.
- 6041 days.

- Daily absolute logreturns of the Japanese yen vs the German mark.
- Jan 1971 Feb 1994.
- 6041 days.







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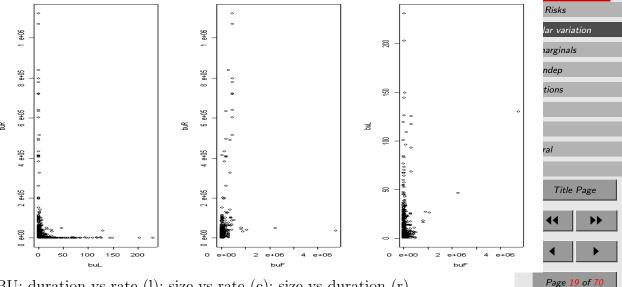


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Boston Univ http request data: size, download rate, duration.



BU: duration vs rate (l); size vs rate (c); size vs duration (r).

α	$\hat{\alpha}_{\mathrm{size}}$	$\hat{\alpha}_{\mathrm{rate}}$	$\hat{\alpha}_{\mathrm{duration}}$
estimated value	1.15	1.13	1.4

Table 1: Tail parameter estimates.

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2.5.1. More flexibility.

A more flexible defin of a multivariate heavy tail is: $\exists b_n^{(i)} \to \infty$ for i = 1, ..., d and \exists Radon ν such that

$$n\mathbb{P}\left[\left(\frac{Z^{(i)}}{b_n^{(i)}}, i = 1, \dots, d\right) \in \cdot \right] \to \nu(\cdot). \tag{3}$$

Theorem. Suppose $\mathbf{Z} \sim F$ and $Z^{(i)} \sim F_{(i)}$. If (3) and

$$n\mathbb{P}\left[\frac{Z^{(i)}}{b_n^{(i)}} \in \cdot \right] \to \nu_{\alpha_i}(\cdot), \quad \nu_{\alpha_i}(x, \infty] = x^{-\alpha_i}, \ x > 0, \alpha_i > 0, \ \forall i,$$

then

$$nF_*(n\cdot) = n\mathbb{P}\left[\left(\frac{\frac{1}{1-F_{(i)}(Z^{(i)})}}{n}, i = 1, \dots, d\right) \in \cdot\right] \to \nu_*(\cdot)$$

where ν_* is *standard*; that is, Radon and

$$\nu_*(tA) = t^{-1}\nu_*(A).$$

Note if for $i = 1, \ldots, d$

$$1 - F_{(i)}(x) \sim x^{-\alpha_i}, \quad x \to \infty,$$

then

$$n\mathbb{P}\Big[\Big(\frac{(Z^{(i)})^{\alpha_i}}{n}, \ i=1,\ldots,d\Big) \in \cdot\ \Big] \to \nu_*(\cdot).$$



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2.5.2. How to get the standard case in practice:

(a) Simple minded. Hope (assume, pray) $1 - F_{(i)}(x) \sim x^{-\alpha_i}$ for all i and then power up. (Slow variation hard (impossible?) to detect in practice and this works reasonably.)

BUT: Must estimate α 's. (Ouch!)

(b) Use ranks method.

<u>BUT</u>: Lose independence among observations.



2.6. Significance of the limit measure.

The limit measure ν_* controls the (asymptotic) dependence structure.

2.6.1. Asymptotic independence.

The distribution F of \mathbf{Z} possesses the property of asymptotic independence if

- 1. $\nu_*((\mathbf{0}, \infty)) = 0$ so that ν_* concentrates on the axes; OR
- 2. S concentrates on $\{e_i, i = 1, \dots, d\}$.

For d=2 this means

$$\mathbb{P}[Z^{(2)} > t | Z^{(1)} > t] = \frac{\mathbb{P}[Z^{(2)} > t, Z^{(1)} > t]}{\mathbb{P}[Z^{(1)} > t]}$$
$$\to (const)\nu_* \Big(\mathbf{1}, \infty\Big] = 0.$$



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Remarks:

- The probability of both components being large is negligible.
- The concept was invented to answer the following query: Let $\{\mathbf{Z}_j, j \geq 1\}$ be iid, non-negative random vectors in \mathbb{R}^d_+ with common distribution F. The necessary and sufficient condition for there to exist $b(n) \to \infty$ such that

$$P[\bigvee_{i=1}^{n} \frac{Z_i^{(l)}}{b(n)} \le x^{(l)}, \ l = 1, \dots, d] \to G(\mathbf{x})$$

is 1 - F is multivariate regularly varying with the original definition. The necessary and sufficient condition for G to be a product distribution is asymptotic independence.

2.6.2. Asymptotic dependence.

The distribution F of \mathbf{Z}_1 possesses the property of asymptotic dependence if

- 1. ν_* concentrates on $\{t\frac{\mathbf{1}}{\|\mathbf{1}\|}: t>0\}$, the diagnonal line, or
- 2. S concentrates on $\{\frac{1}{\|\mathbf{1}\|}\}$.



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Means:

•

$$\mathbb{P}[Z^{(2)} > t | Z^{(1)} > t] \to 1.$$

•

$$G(\mathbf{x}) = G(\wedge_{i=1}^d x^{(i)}),$$

the distribution of a random vector all of whose components are equal.

2.7. Examples

2.7.1. UNC

UNC HTTP response data for (size, rate) for Wednesday afternoons, 1-5:00 pm, April 2001.

Steps:

- Transform (size,rate) data using rank method.
- Convert to polar coordinates.
- Keep 2000 pairs with biggest radius vector.
- \bullet Compute density estimate for angular measure S.



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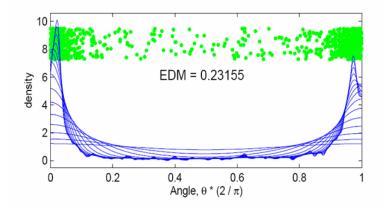
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2.7.2. The Auckland-II trace

(http://pma.nlanr.net/traces/long/auck2.html) a collection of long GPS-synchronized IP header traces captured at the University of Auckland Internet uplink since 1999.

- Connection level data characterized by packet headers.
- connection = 5 tuple (source ip, dest ip, source port, dest port, protocol)
- Amalgamate the data into clusters in hopes that cluster heads are approx Poisson.
 - No unique way to do this.
 - One proposal:
 - * Organize packets into e2e streams—packets with same ip source and destination. Con: ignores application.
 - * Create sessions by clustering e2e streams according to the rule that 2 consecutive packets part of the same cluster if time separation between them is below a threshold.
 - * For a session, compute total payload (S), duration (D) and then (average) rate (R)



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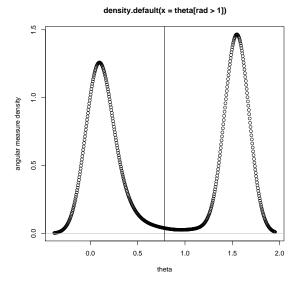


Figure 1: k=1500, Angular measure S,R; length=54343



3. General EV marginals

3.1. Asymptotic method for risk estimation

- As in one dimension, in *d*-dimensions, estimating probabilities of risk regions beyond the range of the data requires an assumption that enables extrapolation.
- Preparation: Interpret operations on vectors componentwise: For \boldsymbol{x} and \boldsymbol{y} vectors in \mathbb{R}^d :

$$-\mathbf{x}\vee\mathbf{y}=(x_i\vee y_i,\,i=1,\ldots,d).$$

$$-\mathbf{x} \wedge \mathbf{y} = (x_i \wedge y_i, i = 1, \dots, d).$$

$$-\mathbf{x} + \mathbf{y} = (x_i + y_i, i = 1, ..., d).$$

$$-\mathbf{x}^{y} = (x_i^{y_i}, i = 1, \dots, d).$$

- And for vectors $\boldsymbol{x}(j)$, $j = 1, \ldots, n$

$$\bigvee_{m=1}^{n} \mathbf{x}(m) = \left(\bigvee_{m=1}^{n} x_1(m), \dots, \bigvee_{m=1}^{n} x_d(m)\right).$$



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• Usual assumption to allow extrapolation beyond the range of the data: \mathbf{X} is in the (multivariate) domain of attraction (DOA) of an extreme value distribution; ie, $\exists a_i(n) > 0, b_i(n) \in \mathbb{R}, i = 1, \ldots, d; n \geq 1$ such that if $\{\mathbf{X}(m), m \geq 1\}$ are iid copies of \mathbf{X} , then

$$P\left[\bigvee_{m=1}^{n} \frac{\mathbf{X}(m) - \mathbf{b}(n)}{\mathbf{a}(n)} \le \mathbf{x}\right] = \left(P\left[\frac{X_i - b_i(n)}{a_i(n)} \le x_i, i = 1, \dots, d\right]\right)^n$$

$$\to G(\mathbf{x})$$

where G is a multivariate EV distribution with non-degenerate marginals. Equivalently, take logs, use $-\log z \sim (1-z)$ as $z \to 1$ and

$$n\left(1 - P\left[\frac{X_i - b_i(n)}{a_i(n)} \le x_i, \ i = 1, \dots, d\right]\right) \to -\log G(\mathbf{x})$$

and this extends to a probability statement about more general sets than just $(-\infty, \mathbf{x}]^c$:

$$nP[\frac{X - b(n)}{a(n)} \in \cdot] \to \nu(\cdot)$$
 (DOA)

where

$$\nu(-\infty, \mathbf{x}]^c = -\log G(\mathbf{x}).$$



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• Tip of the iceberg: If one is determined to use asymptotic methods and \mathcal{R} is the risk region, (DOA) yields a method to estimate the risk probability:

$$P[X \in \mathcal{R}] = P\left[\frac{X - b(n)}{a(n)} \in \frac{\mathcal{R} - b(n)}{a(n)}\right] \approx \frac{1}{n}\hat{\nu}\left(\frac{\mathcal{R} - \hat{b}}{\hat{a}}\right).$$

Note: need $\frac{\mathcal{R}-\boldsymbol{b}(n)}{\boldsymbol{a}(n)}$ to be relatively compact for the asymptotics to work.

The multivariate condition (DOA) implies one dimensional marginals are in a univariate doa. There is a standardized version of (DOA) which expresses the condition as multivariate regular variation on E := [0, ∞] \ {0}: Set

$$U_i(x) = \frac{1}{P[X_i > x]}$$

and

$$\mathbf{X}^* = (U_i(X_i), i = 1, \dots, d).$$

Then marginal convergence in (DOA) to non-degenerate EV distributions plus (DOA) is equivalent to

$$nP[\frac{X^*}{n} \in \cdot] \to \nu^*(\cdot)$$
 (StandRegVarE)



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on
$$\mathbb{E} = [\mathbf{0}, \infty] \setminus \{\mathbf{0}\}$$
 where for $t > 0$,

$$\nu^*(t\cdot) = t^{-1}\nu^*(\cdot).$$

This is just transformation to Pareto scale.

Why this works: Take (DOA) and examine the *i*th marginal convergence:

$$n(1-P[X_i-b_i(n) \le a_i(n)x_i]) \to -\log G_i(x_i), \quad (G_i = ith \text{ marginal of } G),$$

or

$$n/U_i(a_i(n)x_i + b_i(n)) \to -\log G_i(x_i)$$

or

$$\frac{U_i(a_i(n)x_i + b_i(n))}{n} \to \frac{1}{-\log G_i(x_i)}.$$

Take inverses: For y > 0,

$$\frac{U_i^{\leftarrow}(ny) - b_i(n)}{a_i(n)} \to \left(\frac{1}{-\log G_i}\right)^{\leftarrow}(y) =: \psi_i(y).$$



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So for y > 0, if X satisfies (DOA),

$$nP([\frac{\boldsymbol{X}^*}{n} \leq \boldsymbol{y}]^c) = nP([U_i(X_i) \leq ny_i, i = 1, \dots, d]^c)$$

$$= nP([X_i \leq U_i^{\leftarrow}(ny_i), i = 1, \dots, d]^c)$$

$$= nP([\frac{X_i - b_i(n)}{a_i(n)} \leq \frac{U_i^{\leftarrow}(ny_i) - b_i(n)}{a_i(n)}, i = 1, \dots, n]^c)$$

$$\to \nu\left(\left(-\infty, (\psi_i(y_i), i = 1, \dots, d)\right)^c\right)$$

$$= \nu^*\left((\mathbf{0}, \boldsymbol{y}]^c\right).$$

From this we get

$$nP[\frac{X^*}{n} \in A] \to \nu^*(A)$$

for nice sets A.

Note since

$$\nu(-\infty, \mathbf{x}]^c) = -\log G(\mathbf{x}),$$

we have that typically ν (and hence ν^* is an measure with infinite mass.

3.1.1. **Summary.**

(DOA) can be standardized to become (StandRegVarE) using marginal (copula-like) transformations.



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4. Curse of asymptotic independence

• If in (DOA), the limit G is a product

$$G(\mathbf{x}) = \prod_{i=1}^{d} G_i(x_i),$$
 (AsyIndep)

we say X possesses asymptotic independence.

- Reason for the name asymptotic independence: The limit is a product. But **X** may not appear very independent (see example below). Warning: in many ways and for many people this name is an unfortunate choice.
- Unintended consequence of asymptotic independence: (AsyIndep)
 ⇒

$$\nu(\{\mathbf{x}: x_i > y_i(0), x_y > y_j(0)\}) = 0,$$

for all $1 \le i < j \le d$ and thus such a model has no risk contagion since we estimate

P[two or more components of \boldsymbol{X} are large simultaneously $]\approx 0.$

Reason: For d = 2, suppose X_1, X_2 are asymptotically indepen-



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dent so

$$nP([X_1 \le a_1(n)x_1 + b_1(n), X_2 \le a_2(n)x_2 + b_2(n)]^c)$$

$$\to -\log G_1(x_1) + -\log G_2(x_2).$$
 (4)

Also,

$$\begin{cases}
 nP([X_1 \le a_1(n)x_1 + b_1(n)]^c) \to -\log G_1(x_1), \\
 nP([X_1 \le a_2(n)x_2 + b_2(n)]^c) \to -\log G_2(x_2).
\end{cases} (5)$$

Subtract: (4)-(5), do a little set algebra and conclude

$$nP([X_1 > a_1(n)x_1 + b_1(n), X_2 > a_2(n)x_2 + b_2(n)]^c) \to 0.$$

• In standardized form: (StandRegVarE)+(AsyIndep) mean when d = 2,

$$\nu^*(\mathbb{E}_0) = \nu^*((\mathbf{0}, \infty]) = 0,$$

and ν^* concentrates on the positive axes through 0.

• What to do?



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4.1. How common is (AsyIndep)?

Recall data examples for (size, rate). Also:

- For d = 2: If X satisfies (DOA) and $X_1 \perp X_2$ then X possesses (AsyIndep).
- If $X = (X_1, \dots, X_d)$ is Gaussian with

$$corr(X_i, X_j) = \rho(i, j) < 1,$$

then \boldsymbol{X} possesses (AsyIndep) (Sibuya, 1960). Here the marginals of \boldsymbol{X} are Gaussian and

$$G(\mathbf{x}) = \prod_{i=1}^{d} \exp\{-e^{-x_i}\}.$$

- So using the Gaussian dependence copula means you are exposed to (AsyIndep) and lack of risk contagion.
- Let $U \sim U(0,1)$ and define

$$\boldsymbol{X} = \left(\frac{1}{U}, \frac{1}{1 - U}\right).$$

Since 1/U and 1/(1-U) cannot be simultaneously large, \boldsymbol{X} possesses (AsyIndep). The marginals of \boldsymbol{X} are Pareto and

$$G(\mathbf{x}) = \exp\{-(x_1^{-1} + x_2^{-1})\}, \quad \mathbf{x} > \mathbf{0}.$$



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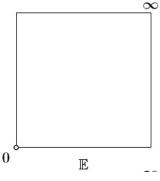


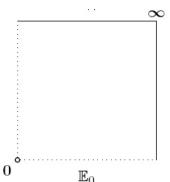
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5. Strategy and Directions





(AsyIndep) + (StandRegVarE) implies the limit measure $\nu^*(\cdot)$ in Pareto scale concentrates on the axes through **0**.

<u>Hint</u>: Consider the complement of the support of ν^* and seek a lower order regular variation on this new set.

Since ν^* concentrates on axes and puts zero mass on interior of quadrant, seek (hidden) regular variation on the interior $\mathbb{E}_0 = (\mathbf{0}, \infty]$ with index < 1. This would allow non-zero estimate of



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Example. For d = 2: If $\mathbf{X} = (X_1, X_2)$ and $X_1 \perp X_2, X_1, X_2$ iid with

$$P[X_i > y] = y^{-1}, \quad y > 1.$$

Then for $x_1 > 0$, $x_2 > 0$, as $n \to \infty$

$$nP[X_i > nx_i] \to x_i^{-1}, \qquad i = 1, 2,$$

 $nP[X_1 > nx_1, X_2 > nx_2] = \left(nP[X_1 > nx_1]\right)P[X_2 > nx_2] \to 0,$

so \boldsymbol{X} is regularly varying on $\mathbb E$ with index 1 and limit measure concentrating on the axes, and

$$nP[X_1 > \sqrt{n}x_1, X_2 > \sqrt{n}x_2] \to \frac{1}{x_1x_2}, \quad x_1 > 0, x_2 > 0,$$

so X is regularly varying on \mathbb{E}_0 with index 2 and limit measure giving positive mass to $(\mathbf{x}, \infty]$.

<u>Conclude</u> for this example:

- X is regularly varying on $\mathbb{E} = [0, \infty] \setminus \{0\}$ with index 1 and limit measure concentrating on lines through $\{0\}$, and giving zero mass to $(0, \infty]$.
- X is regularly varying on $\mathbb{E}_0 = (\mathbf{0}, \infty]$ with index 2 and the limit measure gives positive mass to $(\mathbf{0}, \infty]$.



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Summary:

Lesson: If the support (eg, axes) of the limit measure is less than the full space (eg, \mathbb{E}):

- peel away the support (axes);
- look for extreme value behavior on what's left (eg, $\mathbb{E} \setminus \{axes\} = \mathbb{E}_0$).



5.1. Directions to pursue

Antecedents: Das et al. (2011); Draisma et al. (2004); Heffernan and Resnick (2005); Ledford and Tawn (1996, 1997); Maulik and Resnick (2005); Mitra and Resnick (2011a,b); Resnick (2002)

- 1. Hidden regular variation (HRV)
 - (a) HRV for d=2.
 - (b) HRV for d > 2. Possibly seek regular variation on a progression of decreasing of cones. Must decide how to specify sequence of cones.
- 2. Hidden domain of attraction (HDA):
 - X satisfies (DOA) so that X^* satisfies (StandRegVarE).
 - (AsyIndep) holds so limit measure $\nu^*(\cdot)$ for X^* concentrates on the axes through **0**.
 - However extreme value behavior other than regular variation holds in the interior of the state space. Eg, $\bigvee_{i=1}^{d} X_i^*$ has a regularly varying distribution but $\bigwedge_{i=1}^{d} X_i^*$ has a distribution in a one dimensional domain of attraction other than Fréchet.



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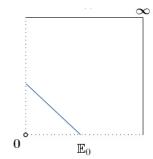
3. What is the unit sphere? The conventional unit sphere may not be compact.

Eg: The L_1 unit sphere is not closed.

What plays the role of the polar coordinate transform

$$x \mapsto \left(\|x\|, \frac{x}{\|x\|}\right)$$

and the spectral distribution.



- 4. More general unifying theory: Seek lower order regular variation on complement of support of the limit measure.
 - Asymptotic full dependence: limit measure concentrates on the diagonal. Remove diagonal and seek regular variation on what is left. Do we need a new theory?
 - What is the unit sphere? What takes the place of the transformation to polar coordinates?
 - What topology is appropriate? What are the *bounded* sets.



5. Estimation?

- Non-parametric approach: Does the rank transform uncover all the hidden structure?
- What sub-cones do we examine?
- How to automate in high dimensions?
- How should we infer the support of the limit measure?



6. Hidden Regular Variation

6.1. d = 2

Suppose $\mathbf{X} = (X_1, X_2)$ satisfies (DOA) and

$$U_i(x) = \frac{1}{P[X_i > x]}, \quad \mathbf{X}^* = (U_1(X_1), U_2(X_2)).$$

So X^* satisfies (StandRegVarE) on $\mathbb{E} = [0, \infty] \setminus \{0\}$; ie,

$$nP[\frac{X^*}{n} \in \cdot] \to \nu^*(\cdot).$$

 X^* has hidden regular variation on $\mathbb{E}_0 = (0, \infty]^2$ if in addition to (StandRegVarE):

- There is a measure $\nu_0^*(\cdot)$ on \mathbb{E}_0 ; and a
- There is a sequence $b_0(n) \to \infty$ such that $b_0(n)/n \to 0$; and
- On \mathbb{E}_0

$$nP[\frac{\boldsymbol{X}^*}{b_0(n)} \in \cdot] \to \nu_0^*(\cdot).$$
 (HRV E0)



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- Q: What sets can we insert in (HRV E0)?
- A: Sets bounded away from the deleted points; ie, sets bounded away from the axes. These are sets in a neighborhood of ∞ .

Consequences

- Because $b_0(n) = o(n)$, X^* and hence X must have (AsyIndep).
- For some $\alpha_0 \geq 1$,

$$b_0(n) \in RV_{1/\alpha_0}.$$

- Hence
 - Distribution tail of max is regularly varying:

$$P[X_1^* \vee X_2^* > x] \in RV_{-1},$$

and

- Distribution tail of min is regularly varying:

$$P[X_1^* \wedge X_2^* > x] \in RV_{-\alpha_0}.$$

This provides a strategy for detection.



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Example 1: $X^* = (X_1, X_2), X_1 \perp X_2$ and

$$P[X_i > x] = x^{-1}, \quad x > 1, i = 1, 2.$$

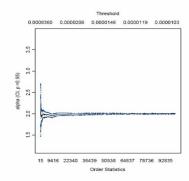
Then $\alpha_0 = 2$. Consider $\boldsymbol{X}_1, \dots, \boldsymbol{X}_{5000}$ iid.

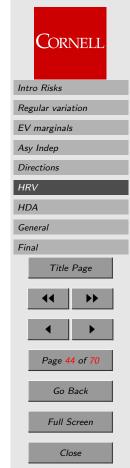
5000 pairs of iid pareto;

$$\alpha = 1; \ \alpha_0 = 2.$$

Hill plot for minima of components.

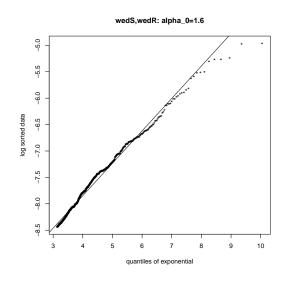
<u>Conclude:</u> Maybe it is possible to detect HRV.





Example 2: UNC Wed (S,R): Response data where S is size of response and R is average transmission rate= size/(download time). Recall angular measure density plot seemed to indicate asymptotic independence.

- Need non-standard model.
- Standardize using rank method.
- QQ plot of minimum component of rank transformed data using 1000 upper order statistics for UNC Wed (S,R).
- Method yields $\alpha = 1$ and estimated $\hat{\alpha}_0 = 1.6$.
- Conclude: For d = 2, detection might be possible





Example 3: Risk calculations.

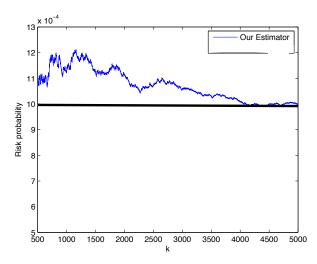
Simulate data: $\{((X_1(n), X_2(n)); 1 \le n \le 5000\}$ iid where

- $X_1(n)$ \perp $X_2(n)$ for each n;
- $X_1(n) \sim \text{Par}(1),$ $X_2(n) \sim \text{Par}(2).$
- Estimate the risk probability (exact value=0.001)

$$P[X_1 > 100, X_2 > \sqrt{10}]$$

 $\begin{array}{ll} \text{with} & spectral & distri-\\ bution & estimator & \text{for}\\ \text{HRV}. \end{array}$

• Conclude: At least in nice cases, this can work.





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Hidden regular variation (continued)

6.2. d > 2:

One way to proceed (Mitra and Resnick, 2011b). Recall $\mathbb{E} = [0, \infty]^d \setminus \{\mathbf{0}\}$. For $\mathbf{x} = (x_1, \dots, x_d) \in \mathbb{E}$, and $l = 1, \dots, d$, let

$$x_{(l)} = l$$
th largest component of x_1, \dots, x_d , $\mathbb{E}_{(l)} = \{ \mathbf{x} \in \mathbb{E} : x_{(l)} > 0 \}.$

So

$$\mathbb{E}_{(1)} = \{ \mathbf{x} \in \mathbb{E} : \bigvee_{i=1}^{d} x_i > 0 \}$$

$$= \mathbb{E},$$

$$\mathbb{E}_{(2)} = \{ \mathbf{x} \in \mathbb{E} : x_{(2)} > 0 \}$$

$$= \{ \mathbf{x} \in \mathbb{E} : \text{ at least 2 components positive } \},$$

etc and

$$\mathbb{E}_{(1)}\supset\mathbb{E}_{(2)}\supset\cdots\supset\mathbb{E}_{(d)}.$$



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Def. Assume $X^* = (X_1^*, \dots, X_d^*)$ satisfies (StandRegVarE) with limit measure $\nu^*(\cdot)$ on \mathbb{E} and scaling function $b_1(n) = n$. For l > 1, X^* has HRV on $\mathbb{E}_{(l)}$ if

1. For some $l > j \ge 1$ (nb. j = 1 is ok), X^* is regularly varying on $\mathbb{E}_{(i)}$ with scaling function $b_i(n)$ and limit measure $\nu_{(i)}(\cdot) \not\equiv 0$, on $\mathbb{E}_{(i)}$ with

$$\nu_{(j)}(\mathbb{E}_{(l)}) = 0, \qquad \nu_{(j)}(\mathbb{E}_{(l-1)}) > 0,$$

AND

2. X^* is regularly varying on $\mathbb{E}_{(l)}$ with scaling function $b_l(n)$ and limit measure $\nu_{(l)}(\cdot) \not\equiv 0$ on $\mathbb{E}_{(l)}$ and

$$b_j(n)/b_l(n) \to \infty.$$

Note $\exists \alpha_{(i)} \leq \alpha_{(l)}$ and

$$\nu_{(j)}(c\cdot) = c^{-\alpha_{(j)}}\nu_{(j)}(\cdot) \qquad \nu_{(l)}(c\cdot) = c^{-\alpha_{(l)}}\nu_{(l)}(\cdot),$$

so the regular variation is of lower order on the smaller cone $\mathbb{E}_{(l)}$ (which makes it hidden).



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Example show:

- Could have HRV on each subcone $\mathbb{E}_{(l)}$, $l=2,\ldots,d$.
- For d = 3, could have
 - Regular variation on $\mathbb{E} = \mathbb{E}_{(1)}$ without asmptotic independence (AsyIndep).
 - No HRV on $\mathbb{E}_{(2)}$ but HRV on $\mathbb{E}_{(3)}$.
 - $-\nu^*(\mathbb{E}_{(1)}) = \nu^*(\mathbb{E}_{(2)}) = \infty, \quad \nu^*(\mathbb{E}_{(3)}) = 0.$
- For d = 3 could have
 - $-X^*$ has regular variation on \mathbb{E} with (AsyIndep).
 - HRV holds on $\mathbb{E}_{(2)}$.
 - No HRV on $\mathbb{E}_{(3)}$.
- For d = 3 possible that
 - $-X^*$ has regular variation on \mathbb{E} .
 - HRV exists on $\mathbb{E}_{(2)}$ but not on $\mathbb{E}_{(3)}$ but yet \boldsymbol{X}^* has regular variation on $\mathbb{E}_{(3)}$.
 - (AsyIndep) holds but $\nu_{(2)}(\mathbb{E}_{(3)}) > 0$.



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7. Hidden Domain of attraction (HDA)

(Mitra and Resnick, 2011a)

Recall: **Example 1:** Let $U \sim U(0,1)$ and define

$$\boldsymbol{X} = \left(\frac{1}{U}, \frac{1}{1 - U}\right).$$

Properties:

- X satisfies (StandRegVarE) on $\mathbb{E} = [0, \infty]^2 \setminus \{0\}$.
- \bullet X possesses (AsyIndep).
- $X_1 \wedge X_2 \leq 2$ so \boldsymbol{X} cannot have HRV.

BUT

- $X_1 \wedge X_2 \leq 2$ belongs to the doa of the (reversed) Weibull EV distribution;
- A property akin to HRV holds on a cone but ...
- the cone is not a subcone of \mathbb{E}).



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Blood and guts:

For $\{(x_1, x_2) \in (-\infty, \infty]^2 : x_1 + x_2 < 0\}$, and large n,

$$nP\left[n(X_1 - 2) > x_1, n(X_2 - 2) > x_2\right]$$

$$= nP\left[1 - \frac{1}{2 + x_2/n} < U < \frac{1}{2 + x_1/n}\right]$$

$$= n\left(\frac{1}{2 + x_1/n} - \left(1 - \frac{1}{2 + x_2/n}\right)\right)$$

$$= \frac{n}{2}\left(-\frac{x_1 + x_2}{2n} + O\left(\frac{1}{n^2}\right)\right)$$

$$\to -(x_1 + x_2)/4 \quad (n \to \infty),$$

and if $x_1 + x_2 > 0$,

$$nP[n(X_1-2) > x_1, \ n(X_2-2) > x_2] \to 0.$$

Hmmmm! Suggests concept of hidden domain of attraction (HDA):



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7.1. HDA: Standard case; d=2.

Suppose d=2 and $\boldsymbol{X}=(X_1,X_2)$ satisfies

- $\bullet \ X_1 \stackrel{d}{=} X_2.$
- (DOA) holds with $\mathbf{b}_n = (b_n, b_n) = b_n \mathbf{1}$ and $\mathbf{a}_n = (a_n, a_n) = a_n \mathbf{1}$ with $a_n > 0$ and

$$nP[\frac{X - b_n \mathbf{1}}{a_n} \in \cdot] \to \nu(\cdot),$$

on $[-\infty, \infty]^2 \setminus \{-\infty\}$ or $[0, \infty]^2 \setminus \{0\}$.

• (AsyIndep) holds:

$$e^{-\nu([\mathbf{x},\mathbf{x}]^c)} = G_1(x_1)G_2(x_2),$$

and additionally,

• there exist positive scaling and real centering constants $\{c_n\}$ and $\{d_n\}$ and a non-zero measure ν_0 on a cone $\mathbb{E}_0 = (\mathbf{0}, \infty]$ or $(-\infty, \infty]$ such that

$$nP[(\mathbf{X} - d_n \mathbf{1})/c_n \in \cdot] \to \nu_0(\cdot) \qquad (n \to \infty).$$
 (ConvE0)

Then X possesses standard case HDA.



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Notes:

1. It is not necessarily the case that the cone $\mathbb{E}_0 \subset \mathbb{E}$. For

$$\boldsymbol{X} = \left(\frac{1}{U}, \frac{1}{1 - U}\right),$$

we have

$$\mathbb{E} = [\mathbf{0}, \infty] \setminus \{\mathbf{0}\}, \quad \mathbb{E}_0 = \{\mathbf{x} \in (-\infty, \infty] : x_1 + x_2 \le 0.\}.$$

2. For standard HDA, both $X_1 \vee X_2$ and $X_1 \wedge X_2$ are in one-dimensional EV doa's with EV parameters γ and γ_0 . Since $X_1 \vee X_2 \geq X_1 \wedge X_2$, $\gamma \geq \gamma_0$.



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3. Since $X_1 \wedge X_2$ is in a doa, set

$$U^{\wedge}(x) = \frac{1}{P[X_1 \wedge X_2 > x]}.$$

Then (ConvE0) can be expressed as standard regular variation on $(0,\infty]$:

$$nP\left[\left(\frac{U^{\wedge}(X_1)}{n}, \frac{U^{\wedge}(X_2)}{n}\right) \in \cdot\right] \to \tilde{\nu}_0(\cdot),$$

where $\tilde{\nu}_0(\cdot)$ is obtained from $\nu_0(\cdot)$ and satisfies

$$\tilde{\nu}^0(c\cdot) = c^{-1}\tilde{\nu}^0(\cdot), \qquad c > 0.$$
 (homog)

(homog) allows disintegration of $\tilde{\nu}^0(\cdot)$ as a product measure in the correct coordinate system and permits definition of a spectral measure.



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4. Suppose $X_1 \neq X_2$ but \boldsymbol{X} satisfies (DOA). Standardize:

$$U_i(x) = \frac{1}{P[X_i > x]}, \quad i = 1, 2$$

and set

$$X^* = (X_1^*, X_2^*) = (U_1(X_1), U_2(X_2).$$

Since X satisfies (DOA), X^* satisfies (StandRegVarE). Assume also (AsyIndep). Can now apply the HDA definition to X^* :

- Ask if there exist positive scaling and real centering constants $\{c_n\}$ and $\{d_n\}$ and a non-zero measure ν_0^* on a cone E_0 such that (ConvE0) holds with X^* replacing X.
- If so, set

$$U^{*\wedge}(x) = \frac{1}{P[X_1^* \wedge X_2^* > x]},$$

and then set

$$\boldsymbol{X}^{**} = (U^{*\wedge}(X_1^*), U^{*\wedge}(X_2^*) = (U^{*\wedge} \circ U_1(X_1), U^{*\wedge} \circ U_2(X_2))$$

- Conclude:
 - The distribution of X^* is standard regularly varying on $[0, \infty] \setminus \{0\}$ and (AsyIndep) holds.
 - $-X^{**}$ has a distribution standard regularly varying on $(0,\infty]$.
 - Ingenuity may be required to do estimation.



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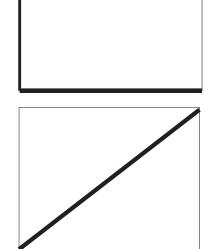
8. General approach.

(Das et al., 2011)

Compare and contrast the two situations thought to be at opposite ends of the spectrum for regularly varying distributions when d = 2.

1. **Asymptotic independence:** limit measure $\nu(\cdot)$ concentrates on axes through **0**. Limit G is a product.

2. Asymptotic full dependence: limit measure $\nu(\cdot)$ concentrates on the diagonal. Limit random vector for maxima has equal components.





- In both cases, the limit measure has a *support* far smaller than $\mathbb{E} = [0, \infty] \setminus \{0\}.$
 - For HRV, remove support and seek a regular variation property on the complement of the support $(0, \infty]$ (when d = 2).
 - Standard case regular variation implies limit measure $\nu^*(\cdot)$ has scaling property:

$$\nu^*(c\cdot) = c^{-1}\nu^*(\cdot), \quad c > 0,$$

which implies

support $\nu^* = \text{closed cone.}$

- This suggests unifying both asymptotic independence and asymptotic full dependence and ... under one theory:
 - Identify support of the limit measure $\nu^*(\cdot)$.
 - Seek lower order regular variation on the complement of the support.



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8.1. Regular variation on cones.

Abandon the one point uncompactification of the positive quadrant; exclude lines through ∞ . Suppose $\mathbb{F} \subset \mathbb{C} \subset [0, \infty)$ are closed cones containing $\mathbf{0}$ and define

$$\mathbb{O} = \mathbb{C} \setminus \mathbb{F}$$
.

 \to The random vector $\mathbf{X} \in \mathbb{C}$ has a distribution with a regularly varying tail on \mathbb{O} if $\exists b(t) \uparrow \infty$ and measure $\nu \not\equiv 0$ on \mathbb{O} such that

$$tP[\frac{\mathbf{X}}{b(t)} \in \cdot] \to \nu(\cdot), \quad \text{on } \mathbb{O}.$$

Let \mathbb{F}_1 be another closed cone containing $\mathbf{0}$ and set

$$\mathbb{O}_1 = \mathbb{C} \setminus (\mathbb{F} \cup \mathbb{F}_1).$$

 \to The random vector $\mathbf{X} \in \mathbb{C}$ has a distribution with hidden regular variation on \mathbb{O}_1 if there is regular variation on \mathbb{O} AND if $\exists b_1(t) \uparrow \infty$ and a measure $\nu_1(\cdot) \not\equiv 0$ on \mathbb{O}_1 such that

$$tP[\frac{\mathbf{X}}{b_1(t)} \in \cdot] \to \nu_1(\cdot), \quad \text{on } \mathbb{O}_1,$$

AND

$$b(t)/b_1(t) \to \infty$$

(which makes the behavior on \mathbb{O}_1 hidden).



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Examples for d=2:

1. Regular variation on the positive quadrant with (AsyIndep):

$$\mathbb{C} = [0, \infty), \quad \mathbb{F} = \{0\}, \quad \mathbb{O} = \mathbb{C} \setminus \mathbb{F} = [0, \infty) \setminus \{0\}.$$

HRV on $(\mathbf{0}, \infty)$:

$$\mathbb{F}_1 = \{(x,0) : x > 0\} \cup \{(0,x) : x > 0\},$$

$$\mathbb{O}_1 = \mathbb{C} \setminus (\mathbb{F} \cup \mathbb{F}_1) = [\mathbf{0}, \infty) \setminus \{\mathbf{0}\} \cup \{\text{lines through } \mathbf{0}\}$$

$$= (\mathbf{0}, \infty).$$



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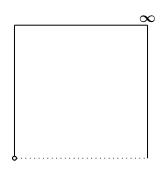
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2. Regular variation on the positive quadrant with conditional extreme value (CEV) model:

$$\begin{split} \mathbb{C} = & [0, \infty), \ \mathbb{F} = \{0\}, \\ \mathbb{O} = & \mathbb{C} \setminus \mathbb{F} = [0, \infty) \setminus \{0\}. \end{split}$$

CEV on \mathbb{D}_{\square} :

$$\begin{split} \mathbb{F}_1 &= \{(x,0): x > 0\}, \\ \mathbb{O}_1 &= \mathbb{C} \setminus (\mathbb{F} \cup \mathbb{F}_1) \\ &= [\mathbf{0}, \infty) \setminus \left(\{\mathbf{0}\} \cup \{(x,0): x > 0\} \right) \\ &= [0, \infty) \times (0, \infty) \\ &= : \mathbb{D}_{\sqcap}. \end{split}$$





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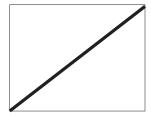
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3. Asymptotic full dependence:

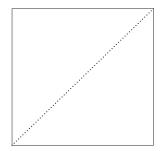
Regular variation on $[0, \infty) \setminus \{0\}$ with limit measure concentrating on diagonal.

$$\begin{split} \mathbb{C} = & [0, \infty), \ \mathbb{F} = \{0\}, \\ \mathbb{O} = & \mathbb{C} \setminus \mathbb{F} = [0, \infty) \setminus \{0\}. \end{split}$$



Remove diagonal:

$$\mathbb{F}_1 = \{(x, x) : x > 0\},
\mathbb{O}_1 = \mathbb{C} \setminus (\mathbb{F} \cup \mathbb{F}_1)
= [\mathbf{0}, \infty) \setminus \{(x, x) : x \ge 0\}$$





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Example 3 (continued): Asymptotic full dependence.

Suppose $X = (X_1, X_2)$ is regularly varying on $[0, \infty) \setminus \{0\}$ with asymptotic full dependence so the limit measure $\nu(\cdot)$ concentrates on $\{(x, x) : x > 0\}$. Suppose

 X_i = one period loss of financial instrument I_i .

Construct the portfolio:

- Buy one unit of I_1 . (Go long.)
- Sell one unit of I_2 . (Go short.)

One period loss for the portfolio is

$$L = X_1 - X_2$$

and for large x, seek

$$P[X_1 - X_2 > x].$$



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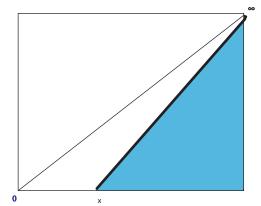
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Under asymptotic full dependence, limit measure concentrates on the line $\{(x,x): x > 0\}$ so we estimate probability as 0:

$$\widehat{P}[X_1 - X_2 > x] = 0.$$

<u>Conclude:</u> A more general theory has applicability.





8.2. Consequences:

- Need for a more general theory of HRV which covers
 - Asymptotic independence.
 - Asymptotic full dependence.
 - Other cases where the support of limit measure is strictly smaller than the state space.
- If doing HRV estimation of the probability of the blue region under asymptotic full dependence:
 - Remove diagonal.
 - But: then the blue region is not relatively compact if include lines through ∞ in state space.
 - ⇒ need to remove lines through ∞ and use different topology [Hult and Lindskog (2006)].
 - Demise of the one-point uncompactification?



8.3. Polar coordinate transform and unit spheres:

• A limit measure ν for standard regular variation on cone $\mathbb O$ satisfies the scaling property:

$$\nu(c\cdot) = c^{-1}\nu(\cdot).$$

• If $T: \mathbb{O} \mapsto (0, \infty) \times \mathbb{A}$ is a bijection $\mathbf{x} \mapsto (r, \mathbf{a})$ satisfying

$$T(c\mathbf{x}) = (cr, \boldsymbol{a}),$$

then the scaling property of $\nu(\cdot)$ translates to a disintegration property in the new coordinates:

$$\nu \circ T^{-1}(dr, d\boldsymbol{a}) = r^{-2}dr\,S(d\boldsymbol{a})$$

is a product measure on $(0, \infty) \times \mathbb{A}$ and

$$S(\cdot) := \nu \circ T^{-1} \big((1, \infty) \times (\cdot) \big)$$

is the spectral measure. Would like $T^{-1}((1,\infty)\times(\cdot))$ to be relatively compact and then S is a finite (probability) measure.

Examples:

 $-[0,\infty)\setminus\{0\}$: Set $T(\mathbf{x})=(\|\mathbf{x}\|,\mathbf{x}/\|\mathbf{x}\|)$ and \mathbb{A} is the (conventional) unit sphere which is compact:

$$\mathbb{A} = \{ \mathbf{x} \in [\mathbf{0}, \mathbf{\infty}) : ||\mathbf{x}|| = 1 \}.$$



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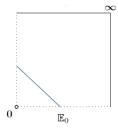
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$$-(\mathbf{0}, \infty)$$
:

The transformation in the previous item does not lead to a relatively compact unit sphere.



so use

$$T(\mathbf{x}) = (x_1 \wedge x_2, \frac{\mathbf{x}}{x_1 \wedge x_2}).$$

The new unit sphere

$$\mathbb{A} = \{ \mathbf{x} \in (\mathbf{0}, \mathbf{\infty}) : x_1 \land x_2 = 1 \},$$

being bounded away from $\mathbf{0}$ is relatively compact and so is



$$T^{-1}((1,\infty)\times(\cdot)) = \{\mathbf{x}\in(\mathbf{0},\infty): x_1\wedge x_2\geq 1\}.$$



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 $-\mathbb{O} = \mathbb{C} \setminus \mathbb{F}$ for closed cones \mathbb{C} , \mathbb{F} . Set

$$T(\mathbf{x}) = \left(\operatorname{dist}(\mathbf{x}, \mathbb{F}), \frac{\mathbf{x}}{\operatorname{dist}(\mathbf{x}, \mathbb{F})}\right), \quad \mathbf{x} \in \mathbb{O}.$$

Then

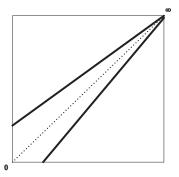
$$\{\mathbf{x} \in \mathbb{O} : \operatorname{dist}(\mathbf{x}, \mathbb{F}) \ge 1\}$$

is bounded away from the deleted $\mathbb F$ and is relatively compact and

$$\mathbb{A} := \{ \mathbf{x} \in \mathbb{O} : \operatorname{dist}(\mathbf{x}, \mathbb{F}) = 1 \}$$

serves as a unit sphere.

Example: \mathbb{F} is the diagonal. Unit sphere is parallel lines to the diagonal.





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9. Final remarks.

- Practical?
 - Limitations of asymptotic methods: rates of convergence?
 - Instead of estimating a risk probability as 0, estimate is a very small number.
- Need for more formal inference for estimation including confidence statements.
- General HRV technique requires knowing the support of the limit measure. Estimate support?
- High dimension problems? How to sift through different possible subcones?
- How to go from standard to more realistic non-standard case; still some inference problems.



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